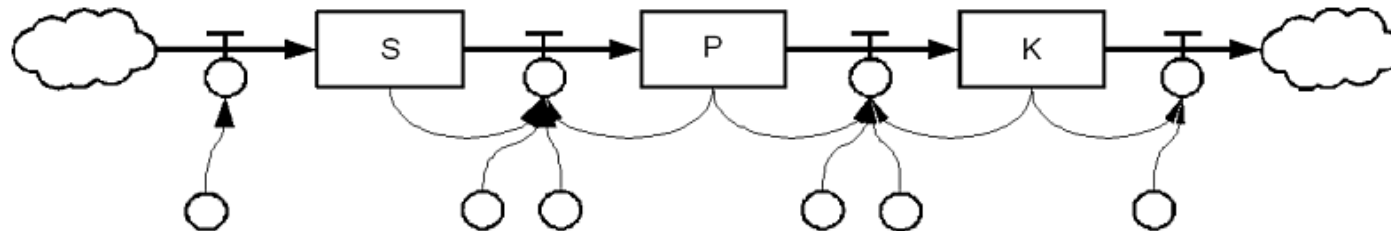


# Dynamic simulation models – is R powerful enough?



## Dynamic models ...

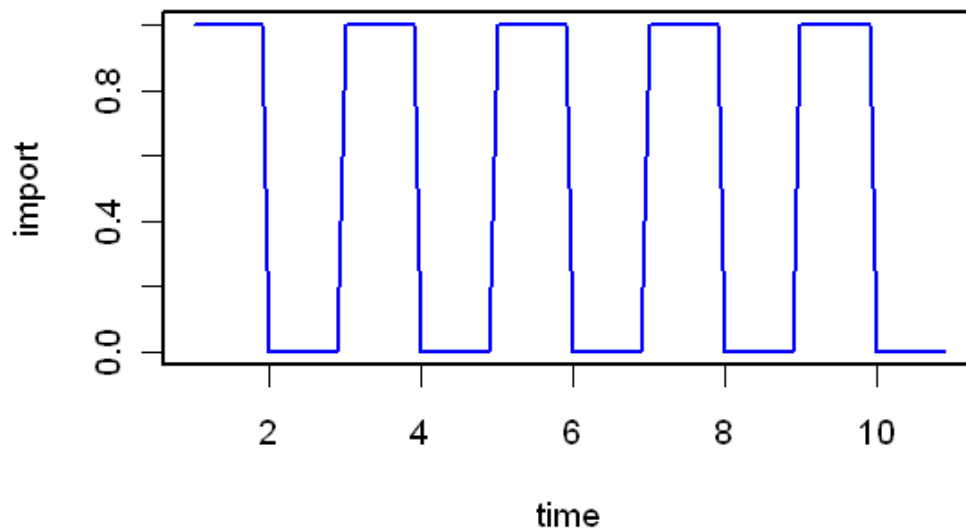
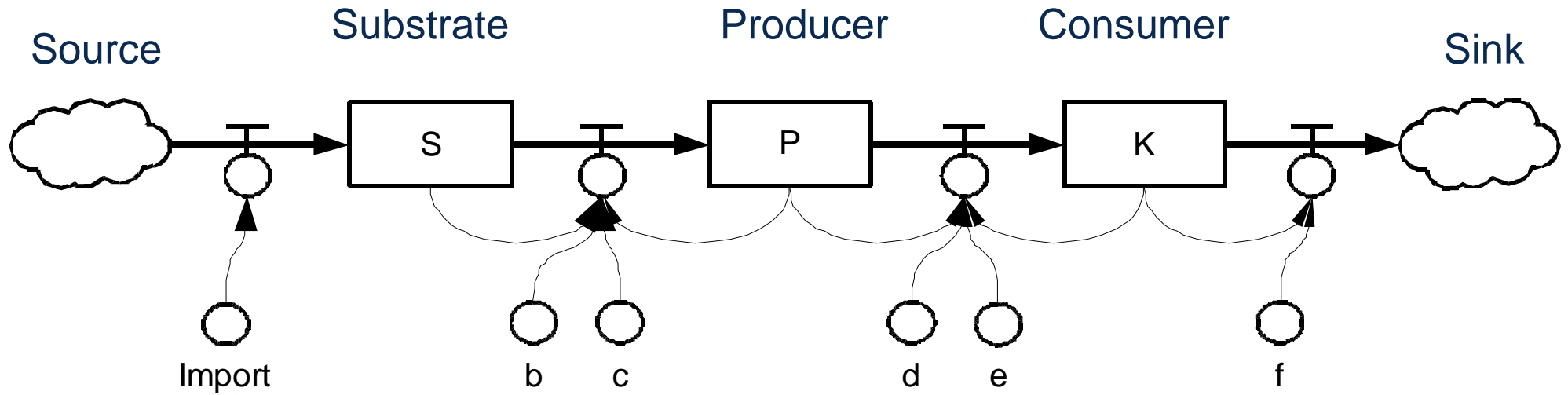
---

$$\frac{dN}{dt} = r \cdot N \cdot \left(1 - \frac{N}{K}\right)$$

- ... models that respect **time explicitly**.
- used in many fields:  
    mathematics, physics, chemistry, biology,  
    ecology, engineering, economics...
- "What makes using **system dynamics** different from other approaches to studying complex systems is the use of **feedback loops** and **stocks** and **flows**. These elements help describe how even seemingly simple systems display baffling **nonlinearity**."

[http://en.wikipedia.org/wiki/System\\_dynamics](http://en.wikipedia.org/wiki/System_dynamics)

# Example 1: A Lotka-Volterra-type model



$$\frac{dS}{dt} = import - b \cdot S \cdot P$$
$$\frac{dP}{dt} = c \cdot S \cdot P - d \cdot P \cdot K$$
$$\frac{dK}{dt} = e \cdot P \cdot K - f \cdot K$$

# The LV-type model in R

---

```
lvmodel <- function(t, x, parms, input) {  
  with(as.list(c(parms, x)), {  
    import <- input(t)  
    dS <- import - b*S*P  
    dP <- c*S*P - d*K*P  
    dK <- e*P*K - f*K  
    list(c(dS, dP, dK))  
  })  
}  
  
# parameters, initial values time steps ...  
# ... and some data, e.g. rectangular signal  
  
sigimp <- approxfun(signal$times, signal$import)  
  
out <- lsoda(init, times, lvmodel, parms, input=sigimp)
```

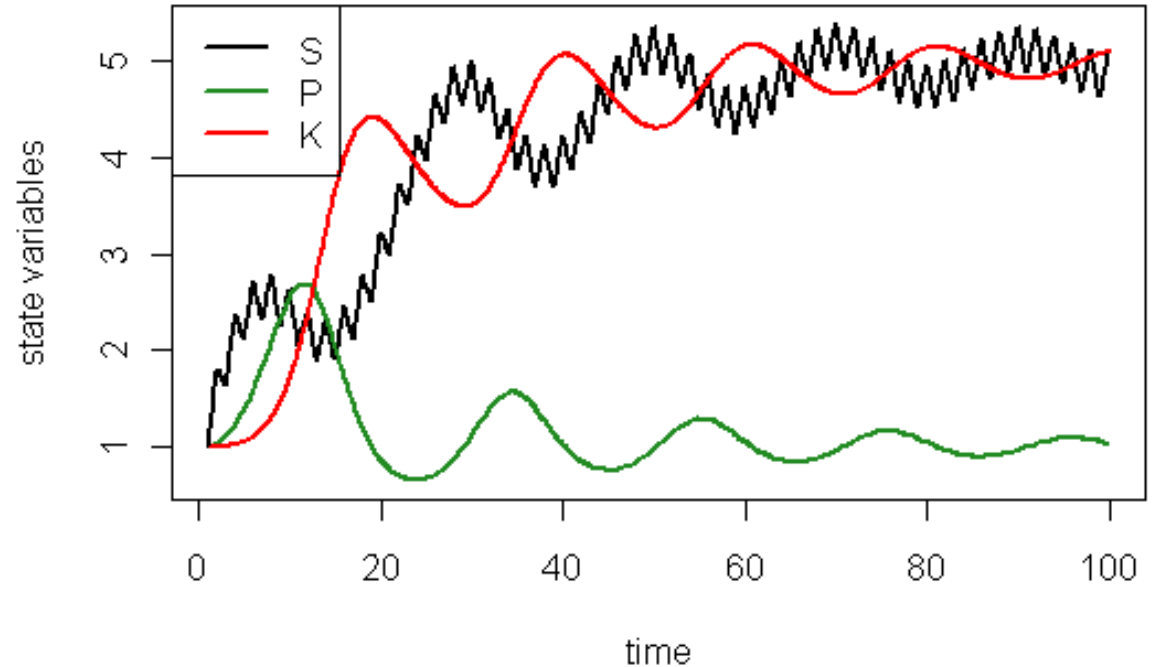
package deSolve (Soetaert, Petzoldt, Setzer)

# Benchmark

$$\frac{dS}{dt} = import - b \cdot S \cdot P$$

$$\frac{dP}{dt} = c \cdot S \cdot P - d \cdot P \cdot K$$

$$\frac{dK}{dt} = e \cdot P \cdot K - f \cdot K$$



**3 equations (ODEs) in R, 1000 (external) timesteps**

**CPU time**

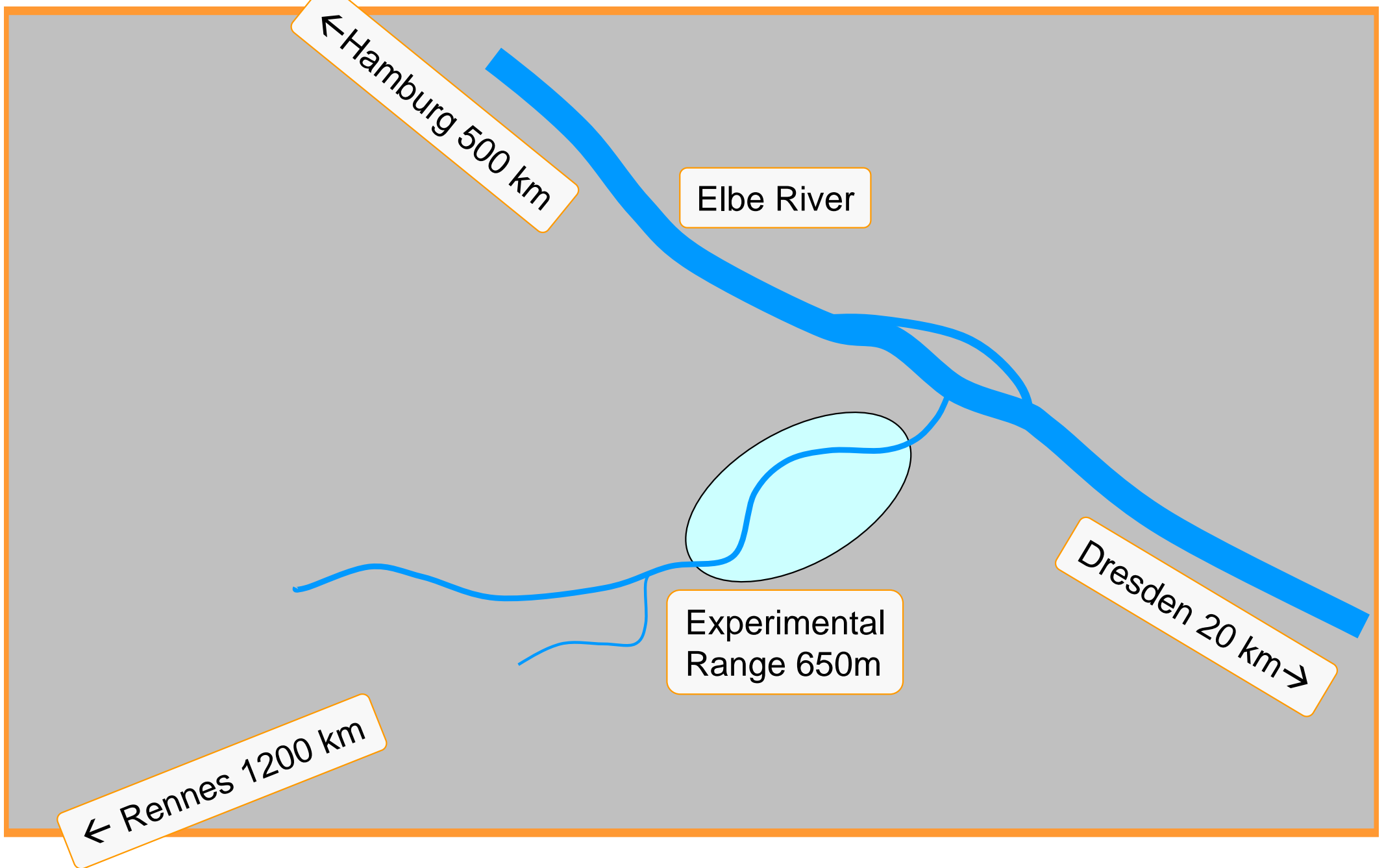
- **case A: interpolated input (approxfun) ..... 1.4 s**
- **case B: import <- if (trunc(t) %% 2 == 0) 0 else 0.1 ..... 0.8 s**

**Time is ok for this toy model, but is R suited for more complex simulations?**

**3 ODEs = 1 s → spatial system with 10.000 ODEs > 1 hour?**

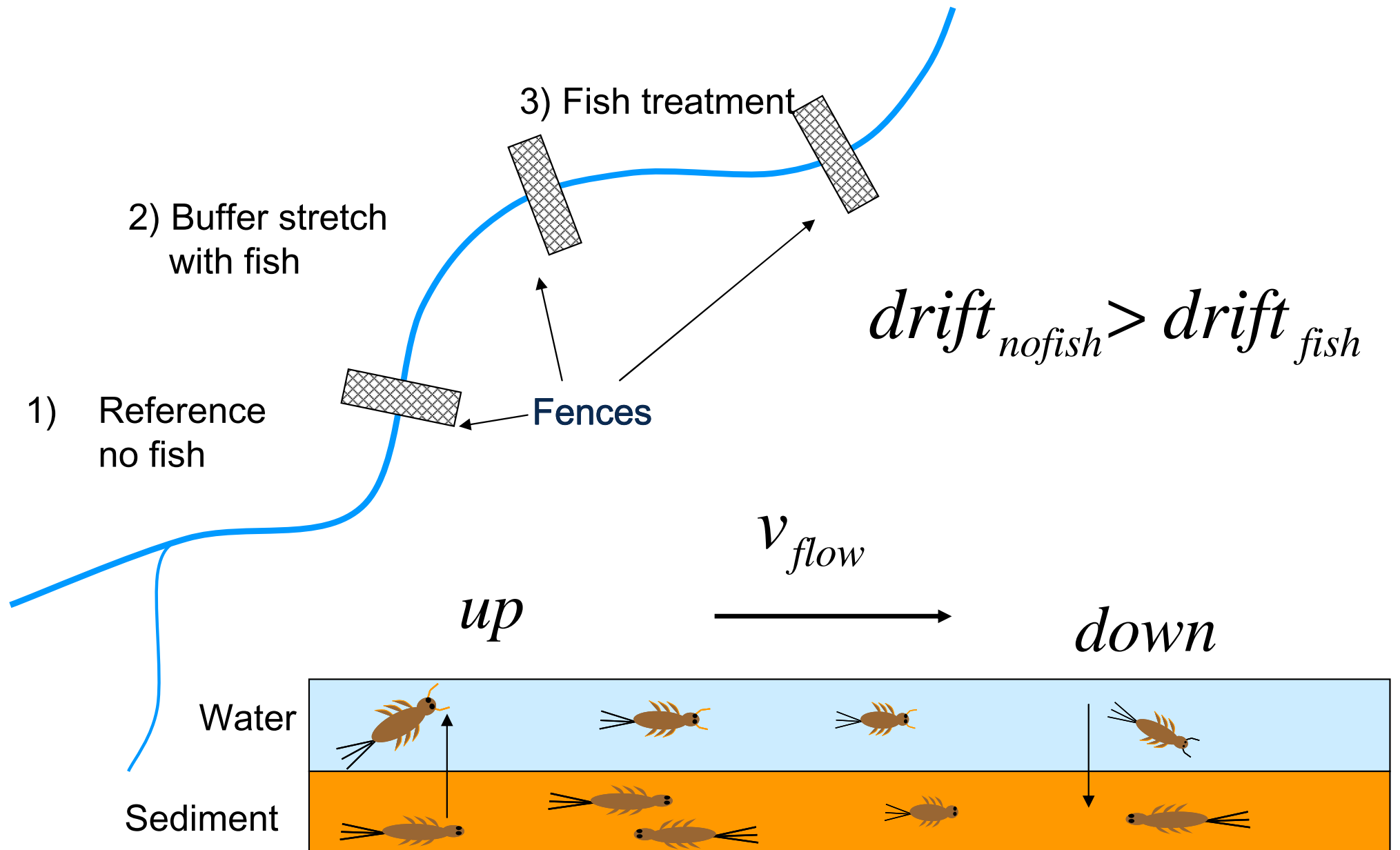
## Example 2: A stream model

Experimentally manipulated small stream of our limnological workgroup



# Downward drift of water insects in the stream (Mayflies)

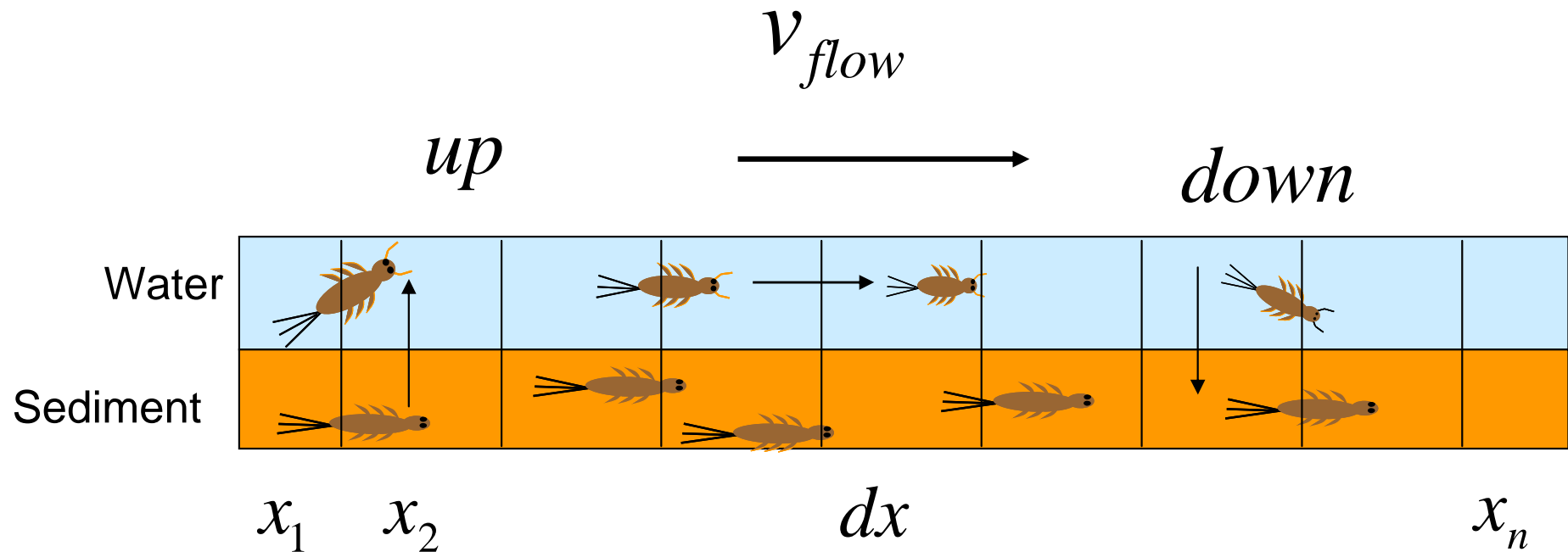
Is buffer stretch sufficiently long?



# Can be described by a basic PDE model

Mobile Organisms  $\frac{\partial M}{\partial t} = up \cdot S - down \cdot M - v \cdot \frac{\partial M}{\partial x}$

Sessile Organisms  $\frac{dS}{dt} = -up \cdot S + down \cdot M$





# The drift model in R: simple structure but 1300 eqs.

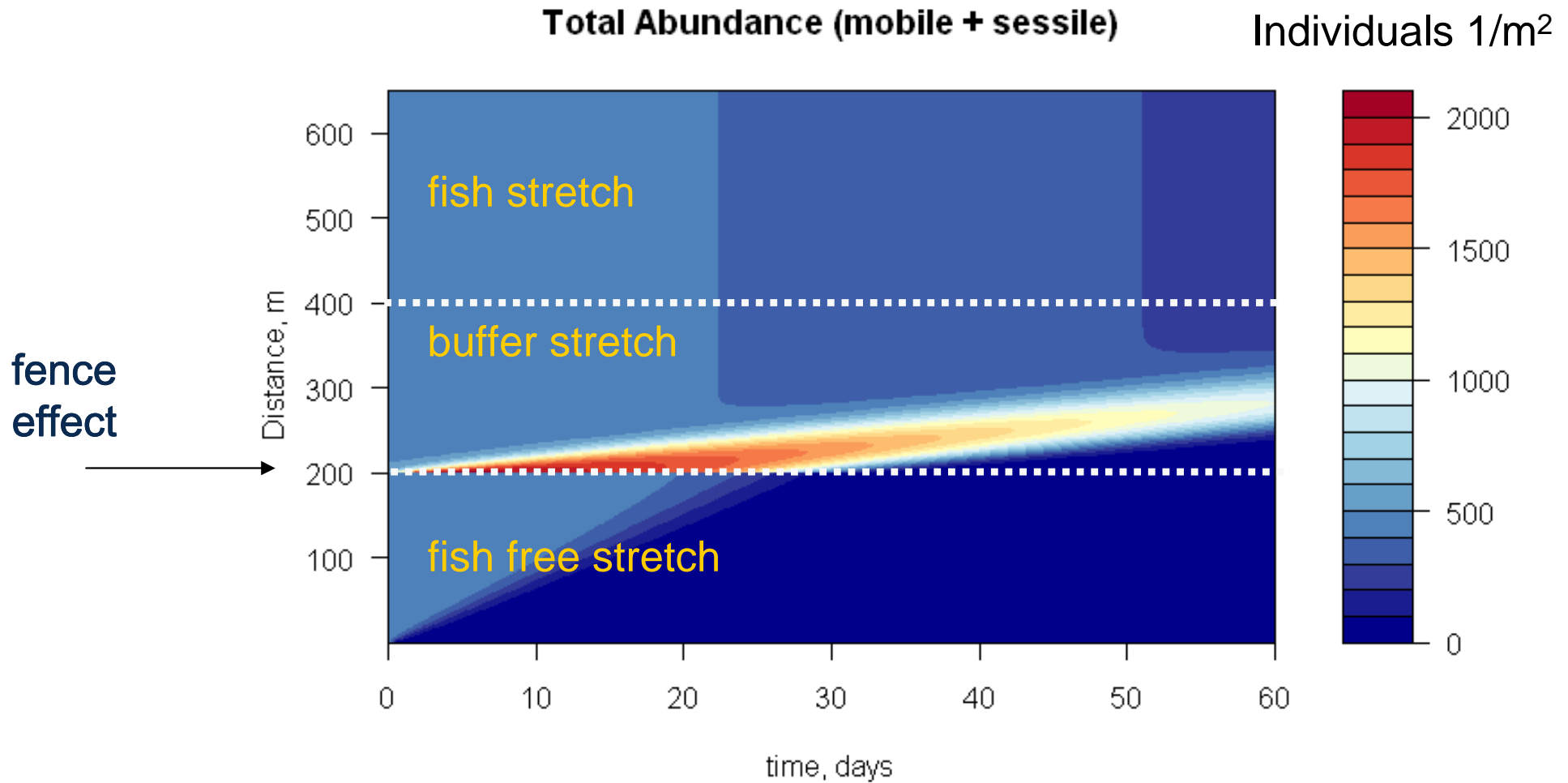
---

```
drift <- function(time, state, parms) {
  S <- state[1:N]           # sessile
  M <- state[(N+1):(2*N)]  # mobile
  dM <- -v * diff(c(0, M))/dx - down * M + up * S
  dS <-                    + down * M - up * S - mort * S
  list(c(dS, dM))
}

dx <- 1                    # grid size [m]
v <- 10000                 # velocity, m/day
x <- seq(dx/2, 650, by = dx) # experimental stretch 650 m
N <- length(x)
up <- c(rep(6.1, 200), rep(1.4, N-200)) # drift rate, 1/d
down <- 8000               # settlement rate, 1/d
mort <- 1e-2               # mortality rate 1/d

## initial conditions (abundance of mayfly larvae)
state <- c(S=rep(500, N), M=rep(0, N))
times <- seq(0, 60, length=101)      # two months

out <- ode.1D(y = state, times, drift, parms = NULL, nspec = 2)
```



- 2 simulated months, 100 external time steps
- model with  $2 \times 650 = 1300$  equations; computation time of ode.1D: ..... **0.6s**

AMD Athlon AM2 X2 6000+, 3000 MHz, 2MB RAM, Windows XP, R-2.10-devel

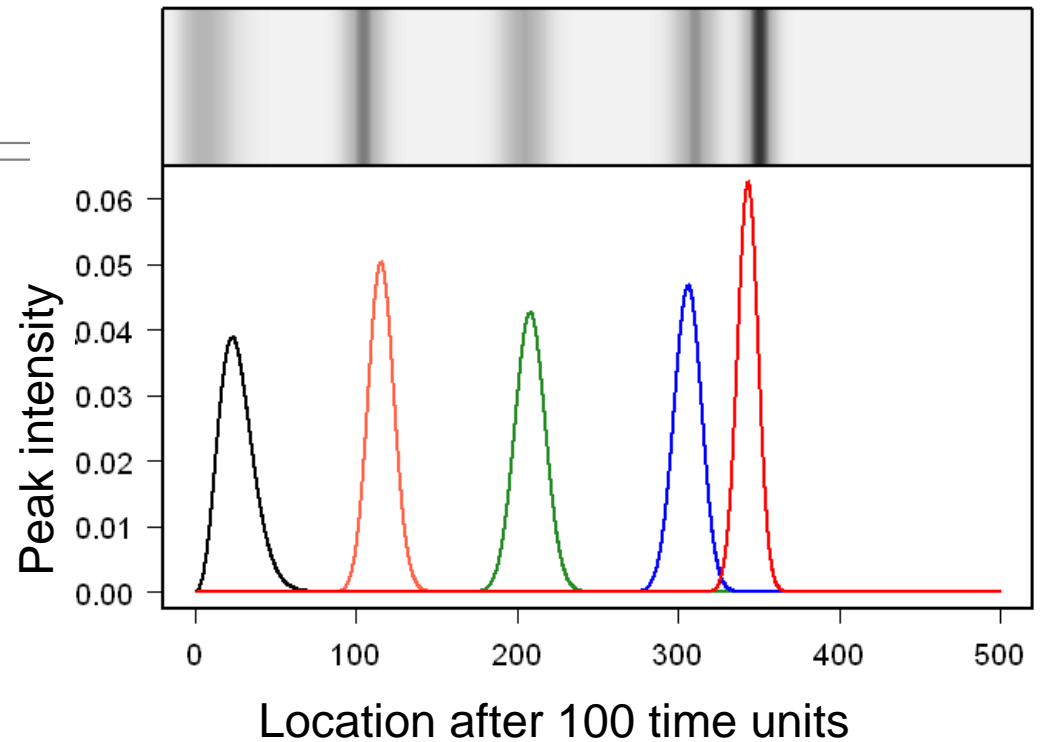
- ➔ **buffer stretch long enough**
- ➔ **R much faster than expected**

# Chromatography model

Similar approach like insect drift  
fixed phase, mobile phase

## Example:

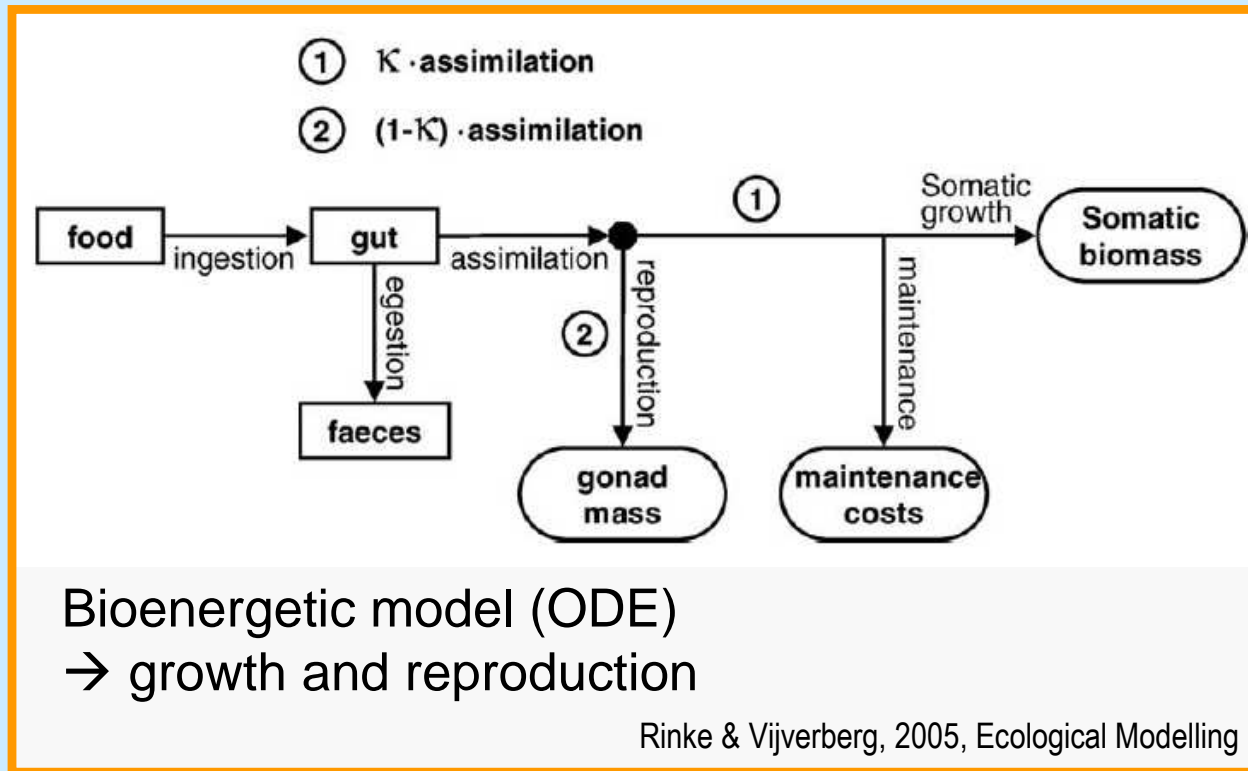
- 5 chemical species,
- 500...5000 grid cells
- 100 external time steps



## Computational Effort:

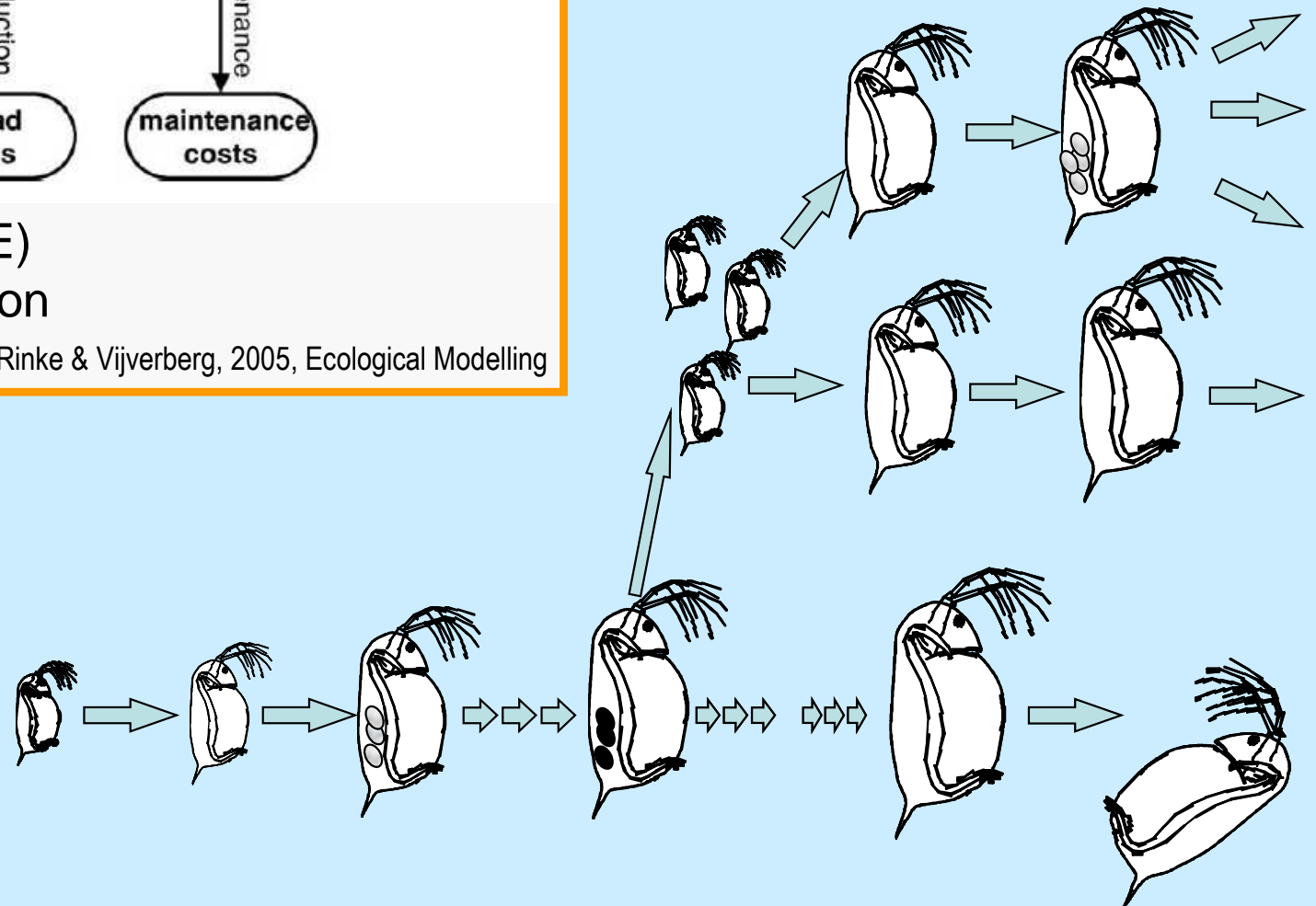
Grid cells	Equations	model in C	model in R
500	$500 * 2 * 5$ = 5,000	0.8 s	1.95 s
5000	$5,000 * 2 * 5$ = 50,000	59 s	66 s

# Example 3: Population dynamics of Daphnia (water flea)



Agent-based simulation

e.g.  
sample of 1000 ... 2000  
individuals  
→ Population dynamics



# Agent-based Daphnia simulation (ABM) with bioenergetic growth model (ODE)



**Effort needed  
per 100  
simulation days:**

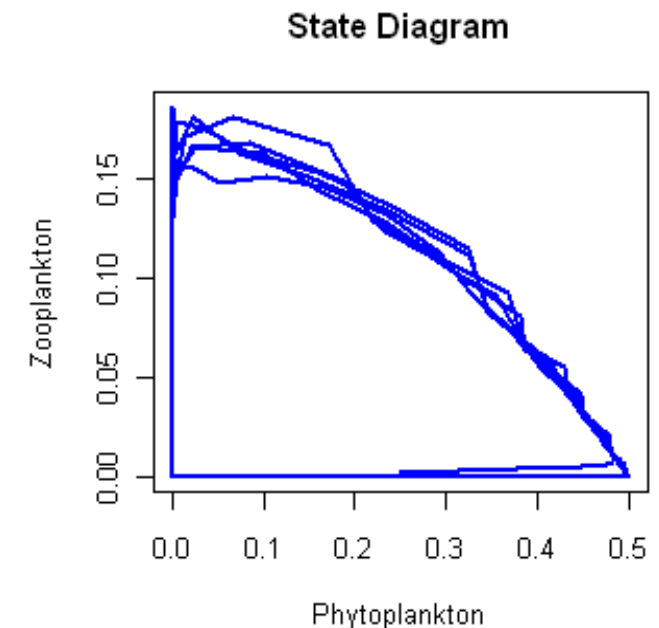
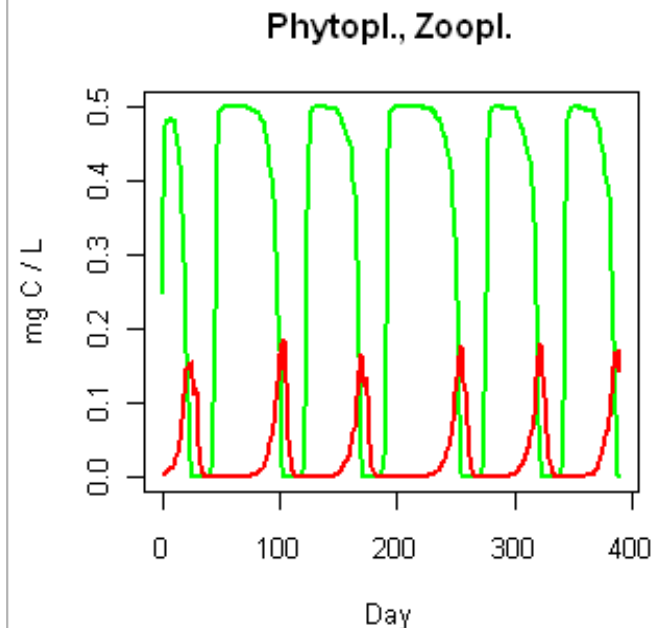
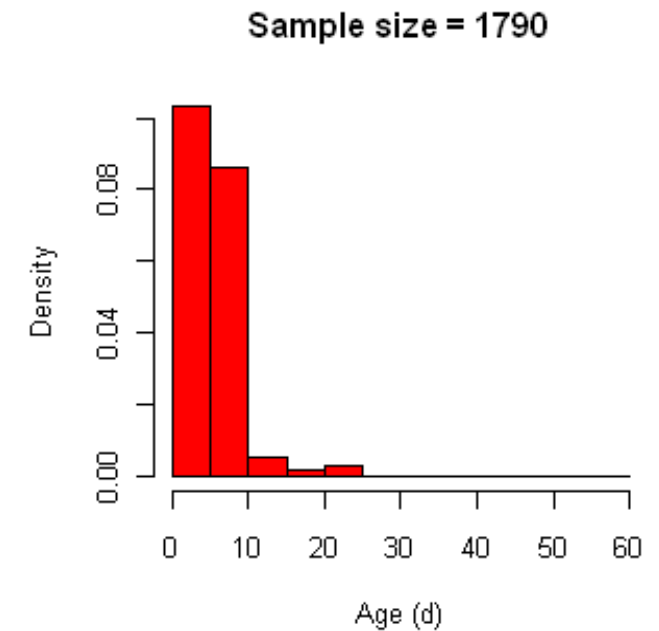
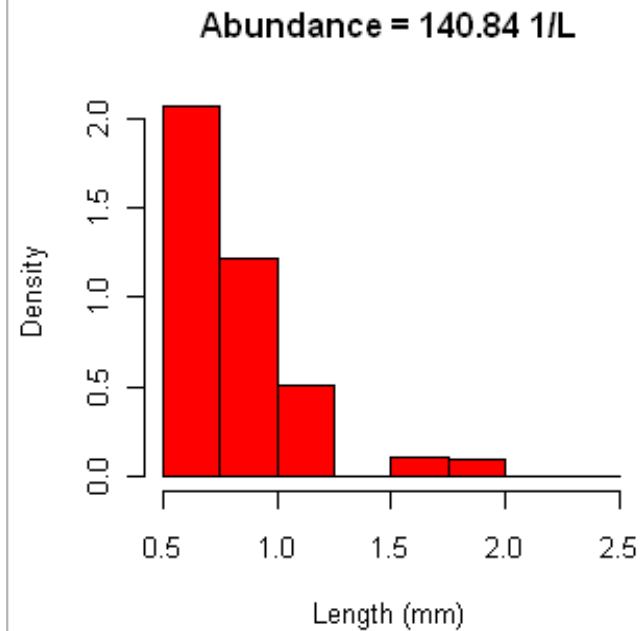
100 ABM time steps  
1000 ODE time steps

1000 ...2000 individuals  
→ 4000 ... 8000 equations

## Performance

pure R: .....136 s

ABM in R,  
ODEs in C: .....65s



# The Lotka-Volterra-type model revisited

## Calling a small model many times

Remember:

3 equations (resource, producer, consumer)

Rectangular external signal (import of resource)

$$\begin{aligned}\frac{dS}{dt} &= import - b \cdot S \cdot P \\ \frac{dP}{dt} &= c \cdot S \cdot P - d \cdot P \cdot K \\ \frac{dK}{dt} &= e \cdot P \cdot K - f \cdot K\end{aligned}$$

Now 10,000 time steps

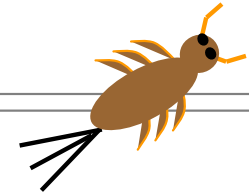
Model in:	R signal with if ... else in model function .....	8 s
	R with approxfun (10,000 rows in data table) .....	65 s
	C, bisectioning, similar to approxfun .....	0.16 s
	C, sequential search in ordered forcings .....	0.03 s

The integrator (Isoda) and the model are able to communicate directly at the machine code level.

➔ Simulation without "friction"

# Efficiency is more than CPU time

---



## □ Programming in R:

- more convenient than C or Fortran
- ... more interactive, more compact code, ...

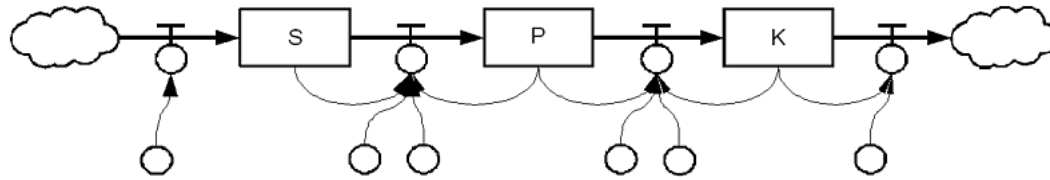
## □ High-level statistical algorithms and graphics

- I can do almost everything in one system
- no need to export / import data to other software
- stats, ... deSolve, FME, ... Sweave
  - support data analysis and report writing

## □ Open Source

- Allows to work with talented people on a global scale
- Enables me to share my code with others (and use theirs)
  - model collection package `simecolModels`

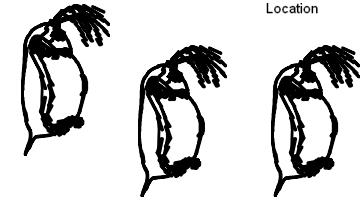
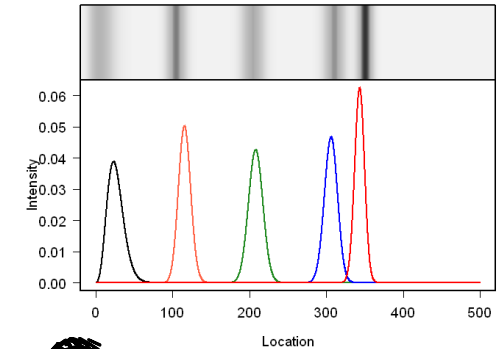
# Conclusion: R is powerful for system dynamics



A few rules:

## ❑ Vectorization! Matrix algebra!

- Large models with identical equations = fast in pure R
- ABMs are efficient with data frames and subset()



## ❑ Avoid unnecessary copying of large objects.

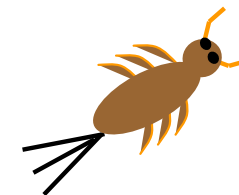
- Sometimes it helps to prefer matrices over data frames.
- Avoid interpolation (i.e. approx),
- If approx is unavoidable, minimize the tables.

## ❑ Complex systems of equations or frequent calls to small models:

- considerable performance gain if **core functions in C or Fortran**
- **consider direct communication** between deSolve and compiled code

## ❑ R is a good investment even in that cases:

- It handles my input and output data
- so I can concentrate on the equations.





Thanks to *useR!*

Karline Soetaert, Woodrow Setzer, Carola Winkelmann

and

Thank You!

package **deSolve** (Soetaert, Petzoldt, Setzer):  
<http://cran.r-project.org/web/packages/deSolve/>

packages **simecol** and **simecolModels**  
<http://www.simecol.de>  
<http://r-forge.r-project.org/projects/simecol/>