Ecological Inference and Higher-Dimension Data Management

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Abstract

Ecological inference (EI) takes contingency tables as the unit of analysis. These tables are described by marginal row and column totals (or proportions); the goal of inference is to determine the joint intra-table relationship between the rows and columns. Using a common example from political science, let the unit of analysis be a voting precinct in a state-wide election:

	Democrat	Republican	No Vote	Total
Black	?	?	?	423
White	?	?	?	219
Hispanic	?	?	?	14
Total	317	156	183	656

For a given election, we estimate each cell (e.g., the number of Blacks who voted for the Democratic candidate) for each precinct i = 1, ..., I, then aggregate across precincts to obtain election-wide results.

While some existing R packages (MCMCpack by Andrew Martin and Kevin Quinn and eco by Kosuke Imai and Ying Lu, for example) offer functions that analyze 2×2 models, we implement more general methods that can take more than two rows or columns. Our package will include:

- Extreme case analysis, or the method of bounds, suggested by Duncan and Davis (1953).
- Ecological regression described in Goodman (1953) using both frequentist point estimates and a Bayesian estimator that produces correct standard errors.
- R × C model described in Rosen et al. (2001) using three estimators: a Bayesian Markov-chain Monte Carlo algorithm, maximum likelihood, and penalized least squares.

Since the unit of analysis (each ecological table) is a matrix rather than a vector, studying the statistical problem of ecological inference requires computational innovation in higher-dimension data management. For example, in the case of the Bayesian $R \times C$ estimator, we need to keep track of an array of dimension:

rows \times columns \times precincts \times simulations

In typical electoral data, there may be four rows (Black, White, Hispanic, Other), three columns (Democrat, Republican, No Vote), and 11,366 precincts (in the case of Ohio in 2004), for a total of 136,392 cell parameters (about 1 GB of memory) *per simulation*. It is thus impossible to store every simulation, or even a substantially thinned number of simulations, without several terabytes of memory (supposing that R could handle that much). We propose to deal with this memory management issue for higher-dimension data in several ways:

- For each iteration (or every iteration saved), the user may specify a quantity of interest to be calculated and stored (rather than the parameter draws themselves).
- Rather than storing draws in the workspace, the Bayesian methods will have the option to sink draws to a file. Since these multi-dimensional data need to be formatted in two dimensions for disk storage, we will provide functions to reconstruct the higher dimensions upon reading the sunk file.

In addition, this package will provide wrapper functions to operate on the margins of higher-dimension arrays, providing useful summary and print functions.

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